DATA STRUCTURES AND ALGORITHMS

Lecture Notes 2

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Recapture

- Asymptotic Notations
 - O Notation
 - Ω Notation

 - o Notation

Big Oh Notation (O)

Provides an "upper bound" for the function *f*

Definition :

T(N) = O (f(N)) if there are positive constants
 c and *n*₀ such that

 $T(N) \leq c f(N)$ when $N \geq n_0$

- T(N) grows no faster than f(N)
- growth rate of T(N) is less than or equal to growth rate of f(N) for large N
- f(N) is an upper bound on T(N)
 - not fully correct !

Omega Notation (Ω)

Definition :

 $T(N) = \Omega$ (f(N)) if there are positive constants *c* and n_0 such that $T(N) \ge c f(N)$ when $N \ge n_0$

- T(N) grows no slower than f(N)
- growth rate of T(N) is greater than or equal to growth rate of f(N) for large N
- f(N) is a lower bound on T(N)
 - not fully correct !

Theta Notation (θ)

Definition :

 $T(N) = \theta (h(N))$ if and only if T(N) = O(h(N)) and $T(N) = \Omega(h(N))$

- T(N) grows as fast as h(N)
- growth rate of T(N) and h(N) are equal for large N
- h(N) is a tight bound on T(N)
 - not fully correct !

Little o Notation (o)

Definition :

T(N) = o(p(N)) if $T(N) = O(p(N)) \text{ and } T(N) \neq \theta(p(N))$

- p(N) grows strictly faster than T(N)
- growth rate of T(N) is less than the growth rate of p(N) for large N
- p(N) is an upperbound on T(N) (but not tight)
 - not fully correct !

ROAD MAP

- Model
- What to Analyze ?
- Running Time Analysis
- General Rules
- Recursive Calls
- Maximum Subsequence Sum Problem
- Binary Search
- Experimentally checking analysis

MODEL

- A formal framework for analysis (simplify the real computers)
- There are many models
 - Automata
 - Turing Machine
 - RAM

MODEL

We use RAM model (normal computer)

- addition
- multiplication
- comparison

take a unit time

- assignment
- fixed size word (32 bit)
- no complicated operation supported
 - requires an algorithm (algorithm may not take unit time)

What to Analyze ?

- Running Time (most important !)
- Required memory space

Run-time complexity is effected by

- compiler
- usually effects the constants &
 computer
 lower order terms

algorithm } use asymptotic notation

Running Time Analysis

- Emprical \rightarrow after implementation
- Theoritical \rightarrow before implementation
- If there are many algorithms ideas, we need to evaluate them without implementation
- We will use 0-notation
 - drop constants
 - ignore lower order terms

Running Time Analysis

Example:

```
int sum (int N)
{
    int i, partialsum; \rightarrow does not count
    partialsum = 0; \rightarrow 1
    for (i=1; i<=N; i++) \rightarrow 1+(N+1)+N
        partialsum+=i*i*i; \rightarrow 3N
    return partialsum; \rightarrow 1
}
= 5N + 4
= \theta(N)
```

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General Rules

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RULE 1 : For Loops

The running time of a for loop is at most the running time of the statements in the for loop times the number of iterations

```
int i, a = 0;
for (i=0; i<n; i++)
{
    print i;
    a=a+i;
}
return i;</pre>
```

 $T(n) = \theta(n)$

RULE 2 : Nested Loops

Analyze nested loops inside out

Example :

```
for (int i=1;i<=q;i++)
{
   for (int j=1;j<=r;j++)
        k++;
   }
} θ(r)</pre>
```

 $T(n) = \theta(r^*q)$

RULE 3 : Consequtive Statements

Add the running times



RULE 4 : If / Else



Running time is never more than the running time of the test plus larger of the running times of S1 and S2

(may overestimate but never underestimates)

 $T(n) \le T_3(n) + max (T_1(n), T_2(n))$

$$T_{worst}(N) = \max_{|I|=N} \{T(I)\} \rightarrow usually used$$

$$T_{av}(N) = \sum_{|I|=N} T(I) \cdot \Pr(I) \quad \rightarrow difficult \ to \ compute$$

$$T_{best}(N) = \min_{|I|=N} \{T(I)\}$$

$$T_{worst}$$
 (N) $\geq T_{av}$ (N) $\geq T_{best}$ (N)

 $T(n) = O(T_{worst}(n)) = \Omega(T_{best}(n))$ ¹⁸



 $\begin{array}{l} T_{w} (n) &= T_{3}(n) + \max \left(T_{1}(n), T_{2}(n) \right) \\ T_{b} (n) &= T_{3}(n) + \min \left(T_{1}(n), T_{2}(n) \right) \\ T_{av} (n) &= p(T)T_{1}(n) + p(F)T_{2}(n) + T_{3}(n) \end{array}$

 $p(T) \rightarrow p$ (condition = True) $p(F) \rightarrow p$ (condition = False)

Example :

if (condition) S1;	$ \left. \begin{array}{l} T_3(n) = \theta(n) \\ T_1(n) = \theta(n^2) \end{array} \right. $	T(n)
else S2;	$T_2(n) = \theta(n)$	

1

 $\begin{array}{l} T_{w}(n) = T_{3}(n) + \max \left(T_{1}(n), T_{2}(n)\right) = \theta(n^{2}) \\ T_{b}(n) = T_{3}(n) + \min \left(T_{1}(n), T_{2}(n)\right) = \theta(n) \end{array}$

if $p(T) = p(F) = \frac{1}{2}$ T_{av} (n) = $p(T)T_1(n) + p(F)T_2(n) + T_3(n) = \theta(n^2)$

$$T(n) = O(n^2) = \Omega(n)$$
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RECURSIVE CALLS

$$T(n) = 4 + T(n-1)$$

$$T(n) = 4 + 4 + T(n-2)$$

$$T(n) = 4 + 4 + 4 + T(n-3)$$

$$T(n) = k*4 + T(n-k) \qquad k= n-1 =>$$

$$T(n) = (n-1)*4 + T(n-(n-1))$$

$$T(n) = (n-1)*4 + T(1)$$

$$T(n) = (n-1)*4 + 2$$

$$T(n) = \theta(n)$$

RECURSIVE CALLS

Example 2:

```
Algorithm for fibonacci series
Fib (int N)
{
    if (N<=1)
        return 1;
    else
        return Fib(N-1)+Fib(N-2);
}</pre>
```

T(N) = T(N-1) + T(N-2) + 4 , T(1)=T(0)=2=> T(N) = O(2ⁿ) (by induction)

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Maximum Subsequence Sum Problem

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• Given (possibly negative) integers A₁, A₂,..., A_N, find

$$\max \sum_{\substack{j \leq N \\ k=i}}^{j} A_k$$

-2
 11
 -4
 13
 -5
 -2

 A[2,4]
$$\rightarrow$$
 sum = 20

 A[2,5] \rightarrow sum = 15

There are many algorithms to solve this problem ! 26



- for small N all algorithms are fast
- for large N O(N) is the best

1) Try all possibilities exhaustively

for each i (0 to N-1)

for each j (i to N-1)

compute the sum of subsequence for (i to j) check if it is maximum

 $T(N) = O(N^3)$

Algorithm 1:

int MaxSubsequenceSum(const int A[], int N) int ThisSum, MaxSum, i, j, k; MaxSum = 0;/* 1*/ for(i = 0; i < N; i++) /* 2*/ for(j = i; j < N; j++)</pre> /* 3*/ ThisSum = 0;/* 4*/ for(k = i; k <= j; k++)</pre> /* 5*/ ThisSum += A[k]; /* 6*/ if(ThisSum > MaxSum) /* 7*/ MaxSum = ThisSum; /* 8*/ return MaxSum; /* 9*/

2) How to compute sum of a subsequence

$$\sum_{k=i}^{j} A_{k} = A_{j} + \sum_{k=i}^{j-1} A_{k}$$

 We can use previous subsequence sum to calculate current one in O(1) time

 $T(N) = O(N^2)$

Algorithm 2:

int MaxSubSequenceSum(const int A[], int N) int ThisSum, MaxSum, i, j; 1*/ MaxSum = 018 for(i = 0; i < N; i++) 1* 2*/ ThisSum = 0;/* 3*/ for(j = i; j < N; j++)</pre> /* 4*/ /* 5*/ ThisSum += A[j]; if(ThisSum > MaxSum) /* 6*/ MaxSum = ThisSum; 1% 7*/ /* 8*/ return MaxSum;

3) Compeletely different algorithm ? Divide and Conquer Strategy



Maximum subsequence can be

- in L
- solved recursively
- in R
- in the middle, in both sides largest sum in L ending with middle element

+

largest sum in R begining with middle element

		<pre>static int MaxSubSum(const int A[], int Left, int Right) {</pre>
		int MaxLeftSum, MaxRightSum; int MaxLeftBorderSum, MaxRightBorderSum; int LeftBorderSum, RightBorderSum; int Center, i;
	* 1*/ * 2*/ * 3*/	<pre>if(Left == Right) /* Base Case */ if(A[Left] > 0) return A[Left]; else</pre>
1	* 4*/	return 0;
11	* 5*/ * 6*/ * 7*/	<pre>Center = (Left + Right) / 2; MaxLeftSum = MaxSubSum(A, Left, Center); MaxRightSum = MaxSubSum(A, Center + 1, Right);</pre>
1	* 8*/ * 9*/	<pre>MaxLeftBorderSum = 0; LeftBorderSum = 0 for(i = Center; i >= Left; i) /</pre>
	10/ *11*/ *12*/	LeftBorderSum += A[i]; if(LeftBorderSum > MaxLeftBorderSum) MaxLeftBorderSum = LeftBorderSum; }
1	*13*/ *14*/	<pre>MaxRightBorderSum = 0; RightBorderSum = 0; for(i = Center + 1; i <= Right; i++) </pre>
111	*15*/ *16*/ *17*/	RightBorderSum += A[i]; if(RightBorderSum > MaxRightBorderSum) MaxRightBorderSum = RightBorderSum; }
1	*18*/ *19*/	<pre>return Max3(MaxLeftSum, MaxRightSum,</pre>

Algorithm 4:

int MaxSubsequenceSum(const int A[], int N) int ThisSum, MaxSum, j; ThisSum = MaxSum = 0;/* 1*/ for(j = 0; j < N; j++) /* 2*/ ThisSum += A[j]; /* 3*/ if(ThisSum > MaxSum) 1* 4*/ MaxSum = ThisSum; /* 5*/ else if(ThisSum < 0) /* 6*/ ThisSum = 0;/* 7*/ /* 8*/ return MaxSum;

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Binary Search

int BinarySearch(const ElementType A[], ElementType X, int N)
{
 int Low, Mid, High;

/*	1*/	Low = 0; High = $N - 1$;
/*	2*/	while(Low <= High)
/*	3*/	{ Mid = (Low + High) / 2;
/*	4*/	if(A[Mid] < X)
/*	5*/	Low = Mid + 1;
·		else lise statistic contraction and a statistic contraction of the statistic statistic statistics of the statistic statistics of the stati
/*	6*/	if(A[Mid] > X)
/*	7*/	High = Mid - 1;
10		else
1%	8*/	return Mid; /* Found */
/	- /	}
/*	9*/	return NotFound: /* NotFound is defined as -1 */
1	}	The suble is a store that the the store based and the second second states and the second second second second

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Checking your analysis experimentally

- Implement your algorithm, measure the running time of your implementation
 - check with theoretical results
- When N doubles (2x)
 - linear => 2x
 - quadratic => 4x
 - cubic => 8x

what about logarithm ? O(N) O(N logN) not easy to see the difference !

 $T_t(N) =$ theoretical running time $T_e(N) =$ experimental running time

Let $T_t(N) = O(f(N))$ compute $\frac{T_e(N)}{T_t(N)} = \frac{T_e(N)}{f(N)}$

- if converges to a constant
 f(N) is a tight bound
- if converges to zero
 - not tight bound (overestimate)
- if diverges underestimate

Ν	T _t	Te	T _{e /} T _t

