

# CSCI: 4210/6210 Simulation & Modeling

PDES: Time Warp Mechanism  
Computing Global Virtual Time



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## Outline

- GVT Computations: Introduction
  - » Synchronous vs. Asynchronous
  - » GVT vs. LBTS
- Computing Global Virtual Time
  - » Transient Message Problem
  - » Simultaneous Reporting Problem
- Samadi Algorithm
  - » Message Acknowledgements
  - » Marked Acknowledgment Messages

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## Global Virtual Time

### ● Problems:

#### » Need to Fossil Collect:

- The Time Warp algorithm consumes more and more memory throughout the execution via the creation of new events.
- Need to reclaim memory used for
  - processed events,
  - anti-messages, and the
  - state history that is no longer needed.

#### » Need a mechanism for operations that cannot be rolled back, e.g. I/O cannot be un-done.

### ● Observation:

- » TWLPs only roll back as a result of receiving a message.
- » Positive messages can only be created by an unprocessed or partially processed message.

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## Global Virtual Time

*GVT(t): minimum time stamp among all unprocessed or partially processed messages at wallclock time t.*

### ● Computing GVT trivial if an instantaneous snapshot of the computation could be obtained: compute minimum time stamp among:

- » Unprocessed events & anti-messages within each LP
- » Transient messages (messages sent before time t that are received after time t)

### ● Memory associated with events with a TS equal to GVT cannot be reclaimed because GVT could be equal to the TS of an anti-message that has not been processed.

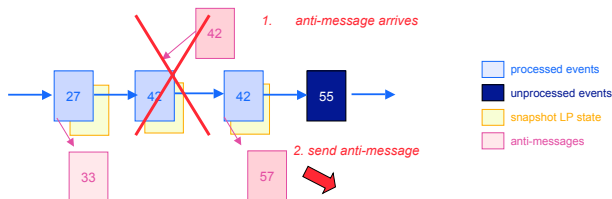
- » Such an anti-message could require one to roll back events with time stamp exactly equal to GVT.

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## GVT = unprocessed anti-message

3. Annihilate message and antimessage



Events with time stamps equal to GVT is needed:

- » GVT is 42, and
- » There are **two processed** events with TS 42.
- » In the first the TWLP processed is canceled by an anti-message with time stamp equal to GVT.

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## Global Virtual Time

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### ● Synchronous vs. Asynchronous GVT computation

- » **Synchronous** GVT algorithms: LPs stop processing events once a GVT computation has been detected
- » **Asynchronous** GVT algorithms: LPs can continue processing events and schedule new events while the GVT computation proceeds "in background"

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## GVT vs. LBTS

*GVT algorithms can be used to compute LBTS and vice versa (assuming a fully connected topology and zero lookahead).*

- GVT algorithms can be used to compute LBTS and vice versa (assuming a fully connected topology and zero lookahead).
- Both determine the minimum time stamp of messages (or anti-message) that may later arrive
  - » Historically, developed separately
  - » Often developed using different assumptions (lookahead, topology, etc.)
- Time Warp
  - » Latency to compute GVT typically less critical than the latency to compute LBTS (need to compute LBTS often).
  - » Asynchronous execution of GVT computation preferred to allow optimistic event processing to continue

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## Asynchronous GVT

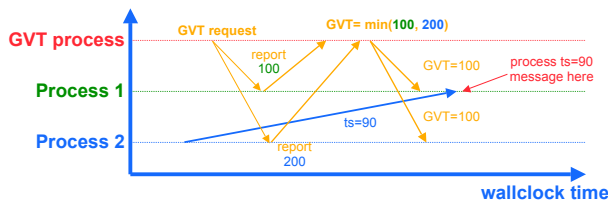
- An incorrect GVT algorithm:
  - » Controller process: broadcast "compute GVT request"
  - » upon receiving the GVT request, each process computes its local minimum and reports it back to the controller
  - » Controller computes global minimum, broadcast to others
- Difficulties:
  - » **transient message problem**: messages sent, but not yet received must be considered in computing GVT
  - » **simultaneous reporting problem**: different processors report their local minima at different points in wallclock times, leading to an incorrect GVT value

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## The Transient Message Problem

- **Transient message**: A message that has been sent, but has not yet been received at its destination
- Erroneous values of GVT may be computed if the algorithm does not take into account transient messages



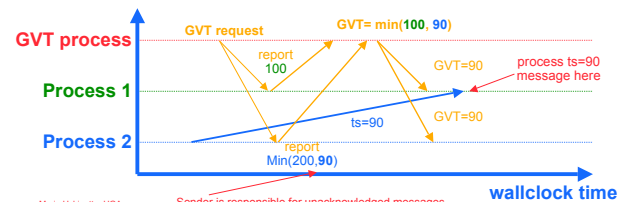
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## Transient Messages: A Solution

*Approach: Ensure every message is accounted for by at least one processor when GVT is being computed:*

- Send an acknowledgement message for each message.
- Sender reports minimum of any unacknowledged messages.
- Receiver takes responsibility as it receives message.



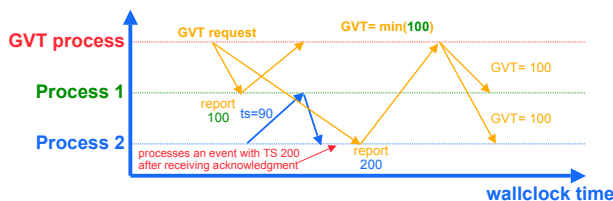
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Sender is responsible for unacknowledged messages

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## Simultaneous Reporting Problem

*Erroneous values of GVT may be computed when processes receive GVT request at different point in time.*



- Process 1 doesn't account for time stamp 90 message
- Process 2 assumes process 1 will account for the message
- Do message acknowledgements solve this problem?
  - » No, at least not by themselves
  - » **Solution**: Mark acks that are sent after local min has been reported

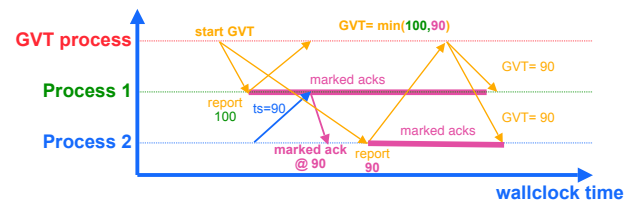
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## Samadi's Algorithm

*Approach: Send an ack for each event & anti-message received, mark acks after the processor has reported its local minimum*

- Controller broadcast "start GVT" message
- Each processor reports minimum time stamp among (1) local messages, (2) unacknowledged sent messages, (3) marked acks that were received
- subsequent acks sent by process are marked until new GVT is received
- controller computes global minimum as GVT value, broadcasts new GVT.



## Summary

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- **Global Virtual Time**

- » **Similar to lower bound on time stamp (LBTS)**
  - Time Warp: GVT usually not as time critical as LBTS
  - Asynchronous GVT computation highly desirable to avoid unnecessary blocking

- **Samadi Algorithm**

- » **Transient message problem: Message acknowledgements**
- » **Simultaneous reporting problem: Mark acknowledgements sent after reporting local minimum**
- » **Requires acknowledgements on event messages**