

# **Stochastic SVD on Hadoop**

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(with thanks to Gunnar Martinsson and Nathan  
Halko of UC Boulder, and Joel Tropp of  
CalTech)

# Lecture breakdown

- Part I
  - Stochastic SVD
- Part II
  - Distributed stochastic SVD

# **Part I: Stochastic SVD**

# Basic goal

- Matrix  $A$ 
  - Find a low-rank approximation of  $A$
  - Basic dimensionality reduction

$$\|A - QQ^*A\| < \epsilon$$



# Basic algorithm

- INPUT:  $A, k, p$
  - OUTPUT:  $Q$
1. Draw Gaussian  $n \times (k + p)$  test matrix  $\Omega$
  2. Form product  $Y = A\Omega$
  3. Orthogonalize columns of  $Y \rightarrow Q$

# Basic evaluation

$$\begin{aligned}\mathbb{E} \|A - QQ^T A\|_2 &\leq \left(1 + \sqrt{\frac{k}{p-1}}\right) \sigma_{k+1} + \frac{e\sqrt{k+p}}{p} \cdot \left(\sum_{j>k} \sigma_j^2\right)^{1/2} \\ &\leq \left[1 + \frac{4\sqrt{k+p}}{p-1} \cdot \sqrt{\min\{m,n\}}\right] \sigma_{k+1} \\ &= C \cdot \sigma_{k+1}.\end{aligned}$$

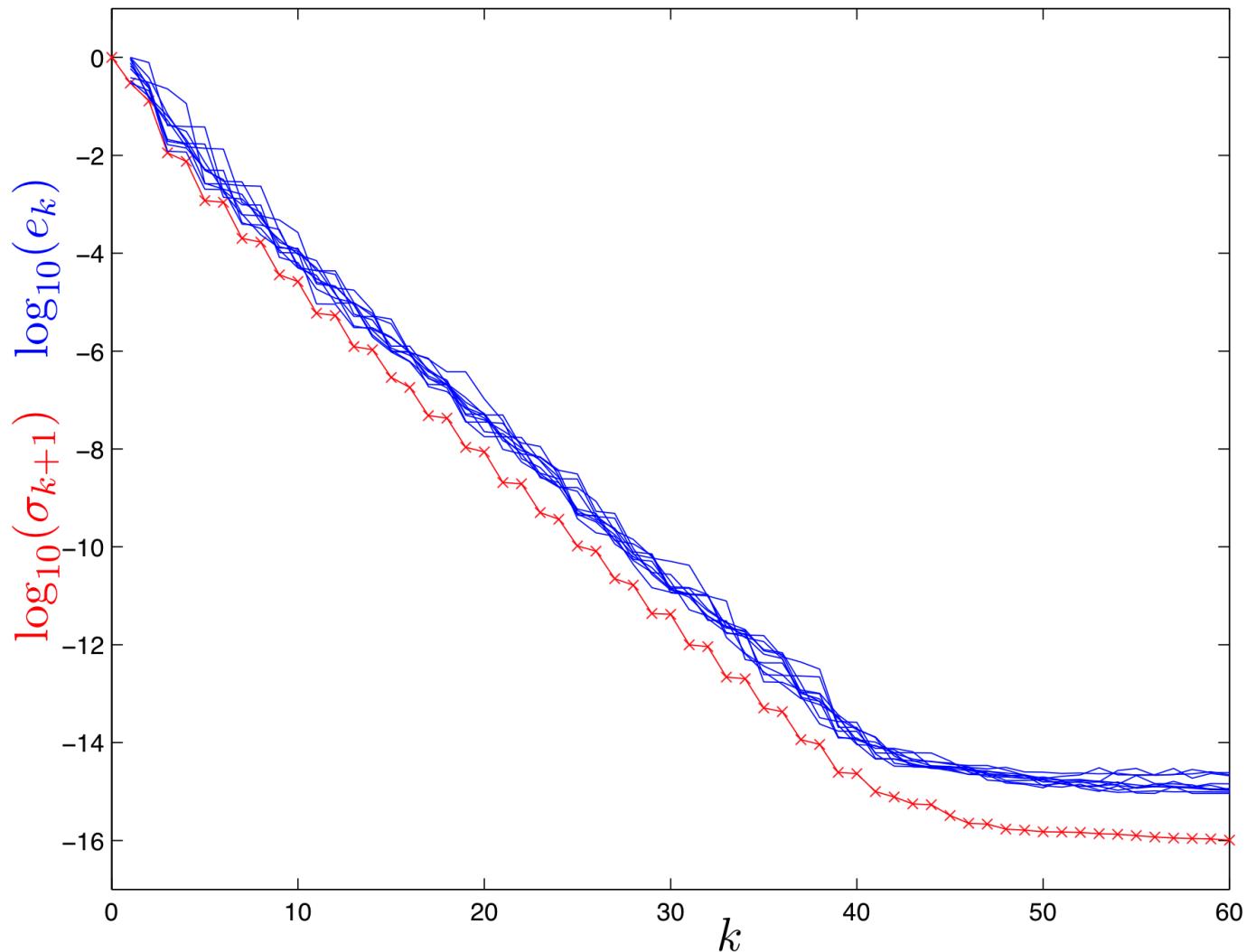
# Approximating the SVD

- INPUT:  $Q$
  - OUTPUT: Singular vectors  $U$
1. Form  $k \times n$  matrix  $B = Q^T A$
  2. Compute SVD of  $B = \hat{U} \Sigma V^T$
  3. Compute singular vectors  $U = Q \hat{U}$

# Demo

# Empirical Results

- 1000x1000 matrix



# Power iterations

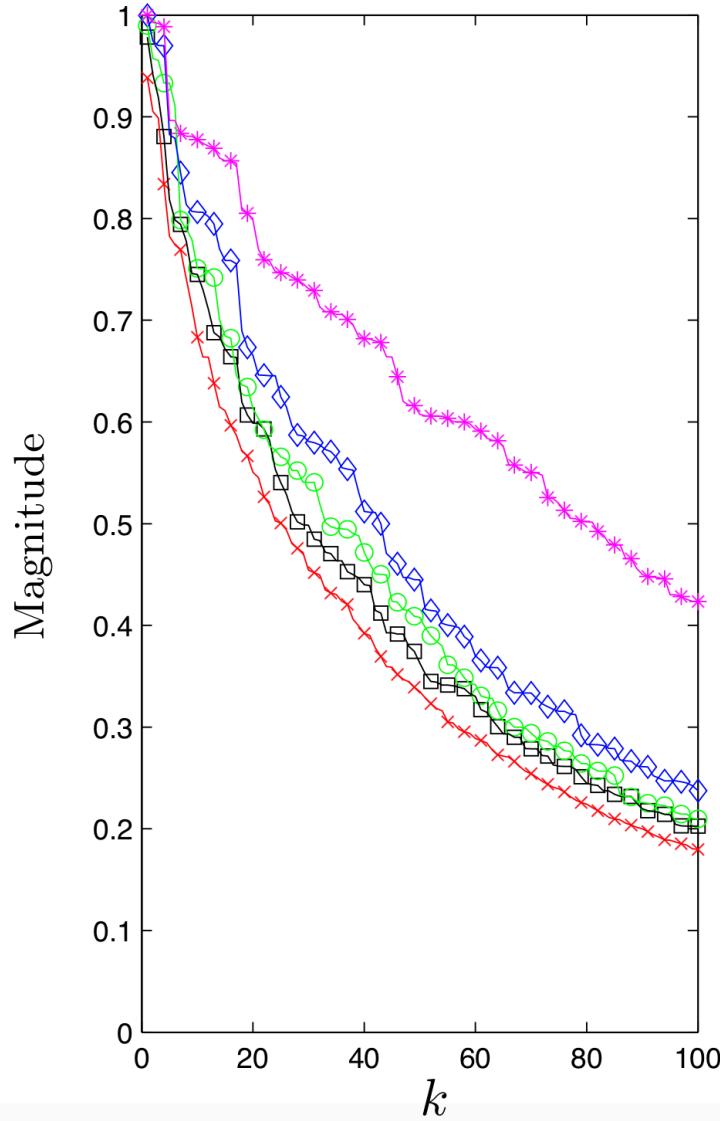
- Affects decay of eigenvalues / singular values

$$Y = \cancel{X} \Omega.$$

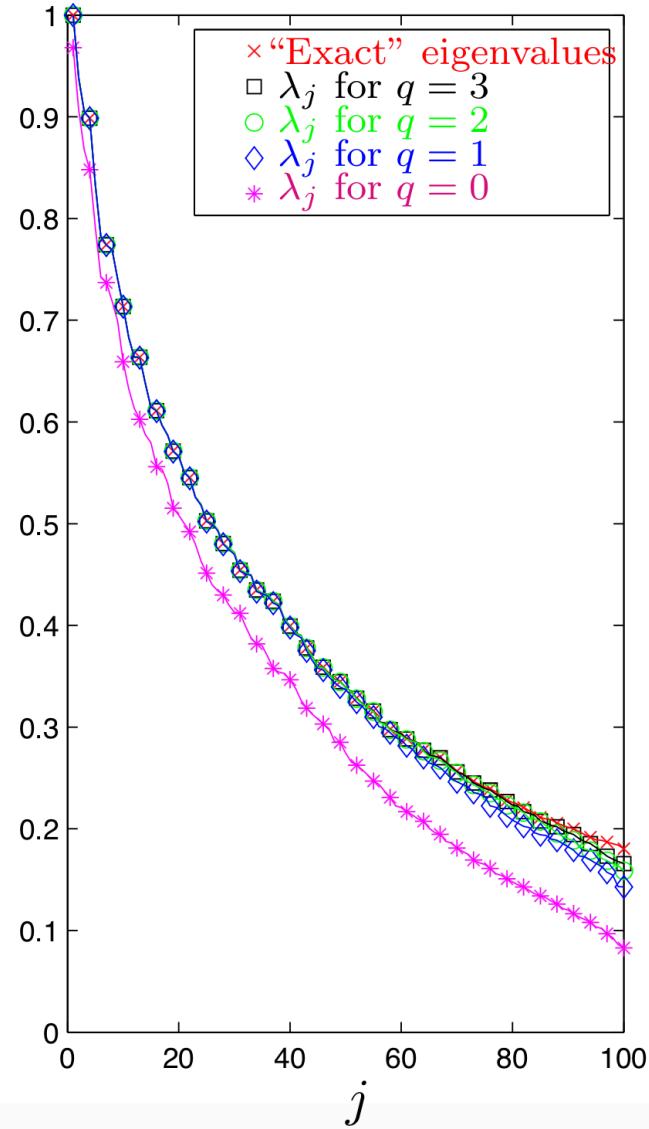
$$Y = (A A^*)^q A \Omega$$

# Empirical Results

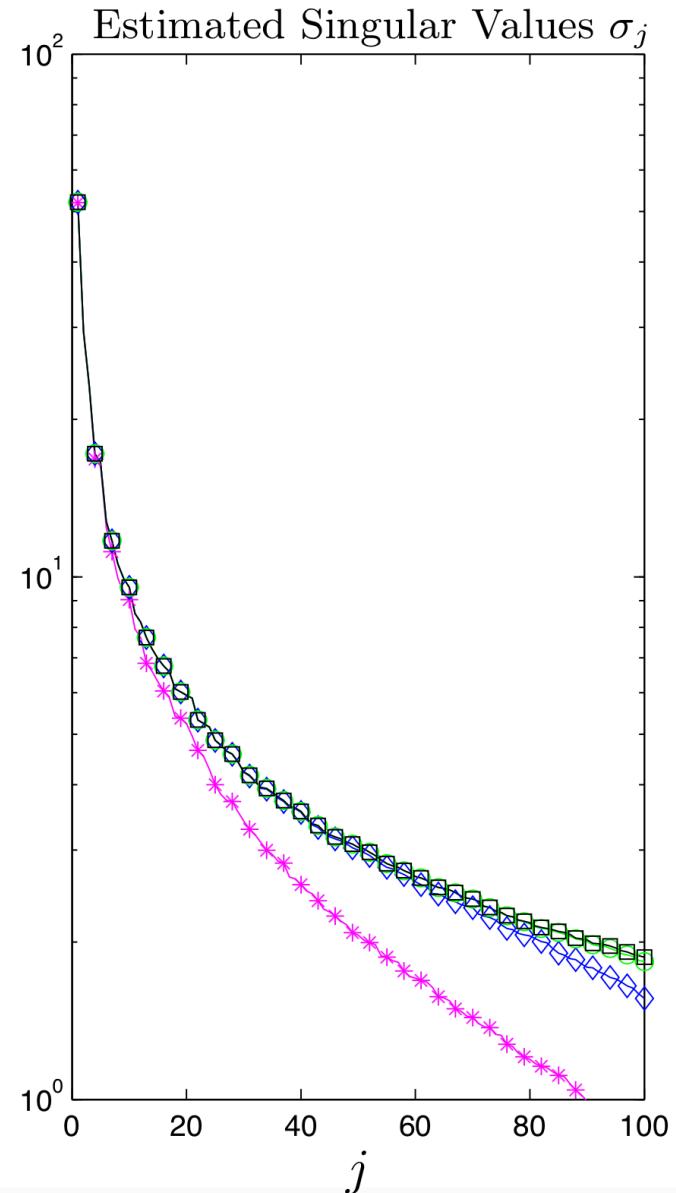
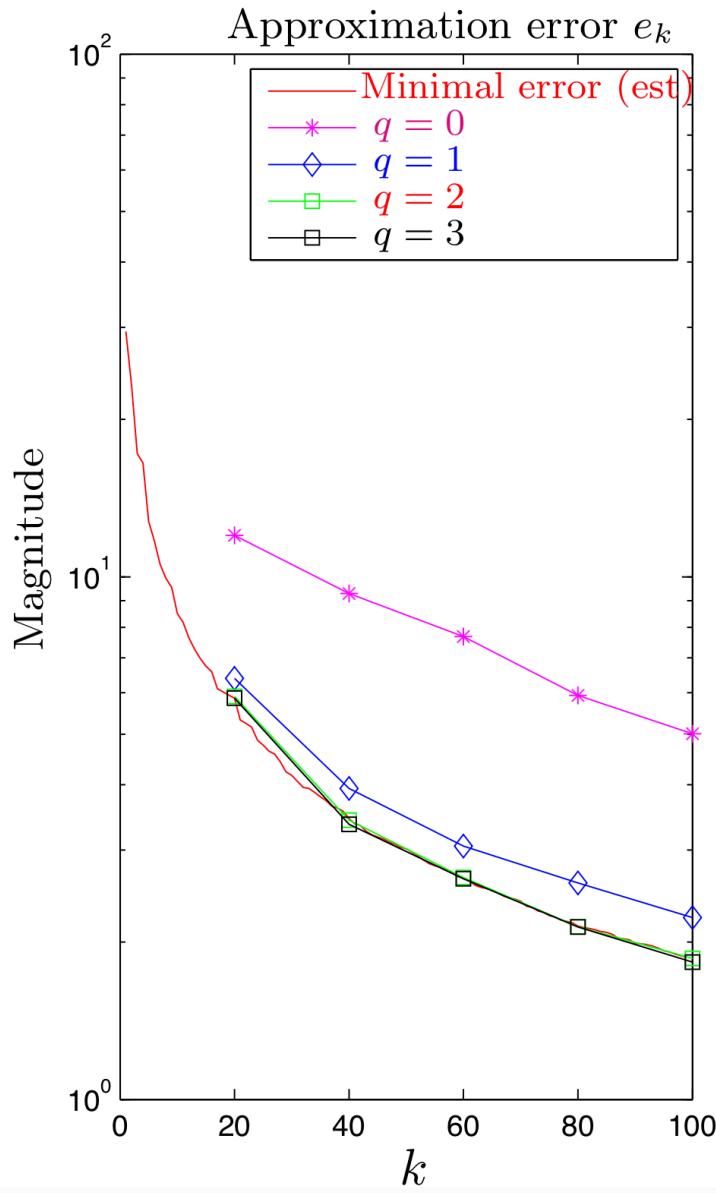
Approximation error  $e_k$



Estimated Eigenvalues  $\lambda_j$



# Empirical Results



# **Part II: Distributed SSVD**

# Algorithm Overview

## ALGORITHM 4.3: STOCHASTIC SINGULAR VALUE DECOMPOSITION

Given an  $m \times n$  matrix  $\mathbf{A}$ , a target rank  $k$ , an oversampling parameter  $p$ , and a number of power iterations  $q$ , the following algorithm computes an approximate rank  $k$  singular value decomposition  $\mathbf{A} \approx \mathbf{U}\Sigma\mathbf{V}^T$ .

Draw an  $n \times k + p$  random matrix  $\Omega$ .

Form the product  $\mathbf{Y} = \mathbf{A}\Omega$ .

Orthogonalize the columns of  $\mathbf{Y} \rightarrow \mathbf{Q}$ .

**for**  $i = 1..q$

    Form the product  $\mathbf{Y} = \mathbf{A}\mathbf{A}^T\mathbf{Q}$ .

    Orthogonalize the columns of  $\mathbf{Y} \rightarrow \mathbf{Q}$ .

**end**

Form the projection  $\mathbf{B} = \mathbf{Q}^T\mathbf{A}$ .

Compute the factorization  $\tilde{\mathbf{U}}\Sigma^2\tilde{\mathbf{U}}^T = \mathbf{B}\mathbf{B}^T$ .

Solve  $\tilde{\mathbf{V}}^T = \Sigma^{-1}\tilde{\mathbf{U}}^T\mathbf{B}$ .

Set  $\mathbf{U} = \mathbf{Q}\tilde{\mathbf{U}}(:, 1:k)$ .

Set  $\mathbf{V} = \tilde{\mathbf{V}}(:, 1:k)$ .

QR factorization

Power iteration

QR factorization

In-core SVD

# SSVD Primitives

- Matrix-vector multiplication:  $\mathbf{y} = \mathbf{A}\mathbf{x}$

## ALGORITHM 4.5: MATRIX MULTIPLICATION $\mathbf{A}\mathbf{x}$

*This algorithm forms the product  $\mathbf{y} = \mathbf{A}\mathbf{x}$  assuming  $\mathbf{A}$  is stored in row major format.*

*Map*

**Iterate**  $\mathbf{A}_{row}$

$$\mathbf{y}_{row} = \langle \mathbf{A}_{row}, \mathbf{x} \rangle$$

**output**  $\mathbf{y}$

- (midterm, anyone?)

# SSVD Primitives

- Matrix-matrix multiplication:  $\mathbf{y} = \mathbf{A}^T \mathbf{A} \mathbf{x}$

## ALGORITHM 4.5: MATRIX MULTIPLICATION $\mathbf{A}^T \mathbf{A} \mathbf{x}$

This algorithm forms the product  $\mathbf{y} = \mathbf{A}^T \mathbf{A} \mathbf{x}$  assuming  $\mathbf{A}$  is stored in row major format.

### *Map*

**Iterate**  $\mathbf{A}_{row}$

$$\mathbf{y}_{partial} = \langle \mathbf{A}_{row}, \mathbf{x} \rangle \cdot \mathbf{A}_{row}^T$$

**output**  $\mathbf{y}_{partial}$

### *Reduce*

$$\mathbf{y} = \sum \mathbf{y}_{partial}$$

**output**  $\mathbf{y}$

# Matrix-matrix multiplication

- Very clever use of map/reduce

$$\begin{aligned} \mathbf{C}\mathbf{x} &= \sum_{i=1}^M \mathbf{A}_i^T (\mathbf{A}_i \mathbf{x}) \\ &= \sum_{i=1}^M \mathbf{v}^{(i)} \\ &= \mathbf{y} \end{aligned}$$

- Each Mapper outputs:  $\langle j, \mathbf{v}_j^{(i)} \rangle$

# SSVD Primitives

- Distributed orthogonalization:  $\mathbf{Y} = \mathbf{A}\Omega$

- Givens rotation

$$G(i, j, \theta) = \begin{bmatrix} 1 & \cdots & 0 & \cdots & 0 & \cdots & 0 \\ \vdots & \ddots & \vdots & & \vdots & & \vdots \\ 0 & \cdots & c & \cdots & -s & \cdots & 0 \\ \vdots & & \vdots & \ddots & \vdots & & \vdots \\ 0 & \cdots & s & \cdots & c & \cdots & 0 \\ \vdots & & \vdots & & \vdots & \ddots & \vdots \\ 0 & \cdots & 0 & \cdots & 0 & \cdots & 1 \end{bmatrix}$$

- Streaming QR
    - Sliding window
  - Merge factorizations
    1. Merge R
    2. Merge  $\mathbf{Q}^T$

# SSVD

## ALGORITHM 4.7: STOCHASTIC SINGULAR VALUE DECOMPOSITION

The ssvd algorithm produces rank  $k$  matrices  $\mathbf{U}, \mathbf{V}, \Sigma$  that form an approximate singular value decomposition of matrix  $\mathbf{A}$ .

1 Q-JOB

2 BT-JOB

for  $i = 1..q$

3 ABT-JOB

BT-JOB

end for

Serial step:

compute  $\tilde{\mathbf{U}}\Sigma^2\tilde{\mathbf{U}}^T = \mathbf{B}\mathbf{B}^T$

4 U-JOB

5 V-JOB

# I: Q-job

## ALGORITHM 4.7.1: Q-JOB

This algorithm forms the product  $\mathbf{Y} = \mathbf{A}\Omega$ , performs the streaming QR factorization and the first level merge.

### *Map*

**Iterate**  $\mathbf{A}_{row}$

$$\mathbf{Y}_{row} = \mathbf{A}_{row} \cdot \Omega$$

$\mathbf{Y}_{row} \rightarrow \text{streamingQR}$

**output**  $\mathbf{Q}_i^{r \times \ell}$  and  $\mathbf{R}_i^{\ell \times \ell}$ .

*merge* $\{\mathbf{Q}_i, \mathbf{R}_i\}_{i=1}^z$

**output**  $\mathbf{Q}^{s \times \ell} \mathbf{R}^{\ell \times \ell}$

## 2: $\mathbf{B}^T$ -job

### ALGORITHM 4.7.2: BT-JOB

This algorithm completes the second level merge and computes the product  $\mathbf{B}^T = \mathbf{A}^T \mathbf{Q}$ . Optionally, partial sums of  $\mathbf{B}\mathbf{B}^T$  are formed and output to disk.

#### **Map**

$$\mathbf{Q}_i \leftarrow \text{merge } \tilde{\mathbf{Q}}_i, \tilde{\mathbf{R}}_1, \dots, \tilde{\mathbf{R}}_M$$

**output**  $\mathbf{Q}_i$  as block of final  $\mathbf{Q}$ .

#### **Iterate** $\mathbf{A}_{row}$

$$\mathbf{B}_{partial}^T = (\mathbf{A}_{row})^T \cdot \mathbf{Q}_{row}$$

**output**  $\mathbf{B}_{partial}^T$

#### **Reduce**

$$\mathbf{B}^T = \sum \mathbf{B}_{partial}^T$$

#### **Option**

$$(\mathbf{B}\mathbf{B}^T)_{partial} = \mathbf{B}_i \mathbf{B}_i^T$$

# 3:AB<sup>T</sup>-job

## ALGORITHM 4.7.3: ABT-JOB

*This algorithm computes the product  $\mathbf{A}\mathbf{B}^T$ , performs the streaming QR factorization and the first level merge.*

### *Map*

**Iterate**  $\mathbf{A}_{row}$

$$\mathbf{A}_{block}(i,:) = \mathbf{A}_{row}$$

**foreach**  $\mathbf{B}_{row}^T$

$$\mathbf{Y}_{partial} = \mathbf{A}_{block}(:,j) \cdot \mathbf{B}_{row}^T$$

**output**  $\mathbf{Y}_{partial}$

### *Reduce*

$$\mathbf{Y} = \sum \mathbf{Y}_{partial}$$

$\mathbf{Y} \rightarrow streamingQR$

**output**  $\mathbf{Q}_i^{r \times \ell}$  and  $\mathbf{R}_i^{\ell \times \ell}$

*merge* $\{\mathbf{Q}_i, \mathbf{R}_i\}_{i=1}^z$

**output**  $\mathbf{Q}^{s \times \ell} \mathbf{R}^{\ell \times \ell}$

# 4: U-job

## ALGORITHM 4.7.4: U-JOB

*This algorithm computes the rank  $k$  factor  $\mathbf{U}$  of the singular value decomposition*

*Map*

**Iterate**  $\mathbf{Q}_{row}$

$$\mathbf{U}_{row} = \mathbf{Q}_{row} \tilde{\mathbf{U}}$$

**output**  $\mathbf{U}_{row}$

# 5:V-job

## ALGORITHM 4.7.5: V-JOB

*This algorithm computes the rank  $k$  factor  $\mathbf{V}$  of the singular value decomposition*

**Map**

**Iterate**  $\mathbf{B}_{row}^T$

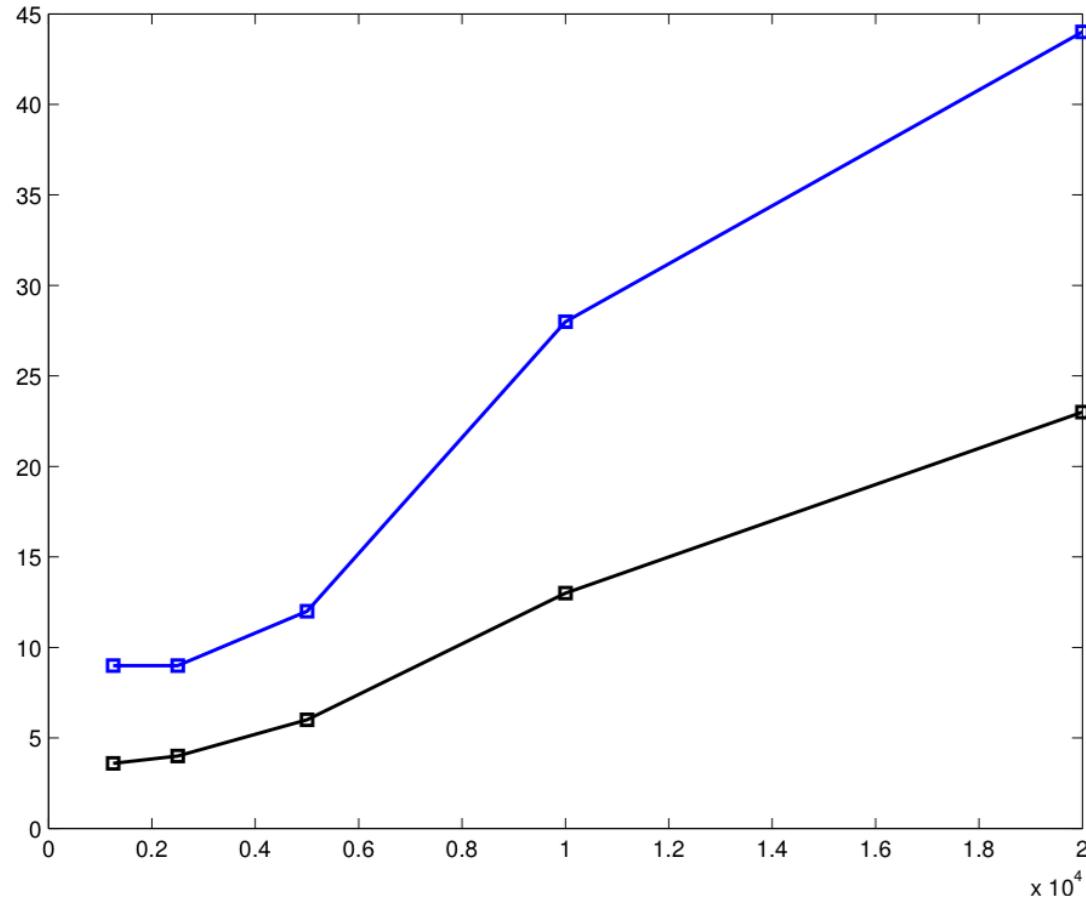
$$\mathbf{V}_{row} = \mathbf{B}_{row}^T \tilde{\mathbf{U}} \Sigma^{-1}$$

**output**  $\mathbf{V}_{row}$

# Mahout SSVD Parameters

parameter	default	description
-rank (-k)	none	decomposition rank
-oversampling (-p)	15	oversampling
-powerIter (-q)	0	number of additional power iterations
-blockHeight (-r)	10,000	Y block height (must be $> (k + p)$ )
-outerProdBlockHeight (-oh)	30,000	block height of outer products during multiplication, increase for sparse input
-abtBlockHeight (-abth)	200,000	block height of $\mathbf{Y}_i$ in ABtJob during $\mathbf{AB}^T$ multiplication, increase for extremely sparse inputs
-reduceTasks (-t)	1	number of reduce tasks (where applicable)
-minSplitSize (-s)	-1	minimum split size

# Block height



blockHeight (-r)	1250	2500	5000	10000	20000
Q-job	9	9	12	28	44
per map	3.6	4	6	13	23

# Power iterations

powerIters

phase	time
Q-job	4
<b>Bt-job</b>	<b>16</b>
<b>ABt-job</b>	<b>12</b>
U-job	2
V-job	2

q	time
0	26
1	52
2	80
3	107

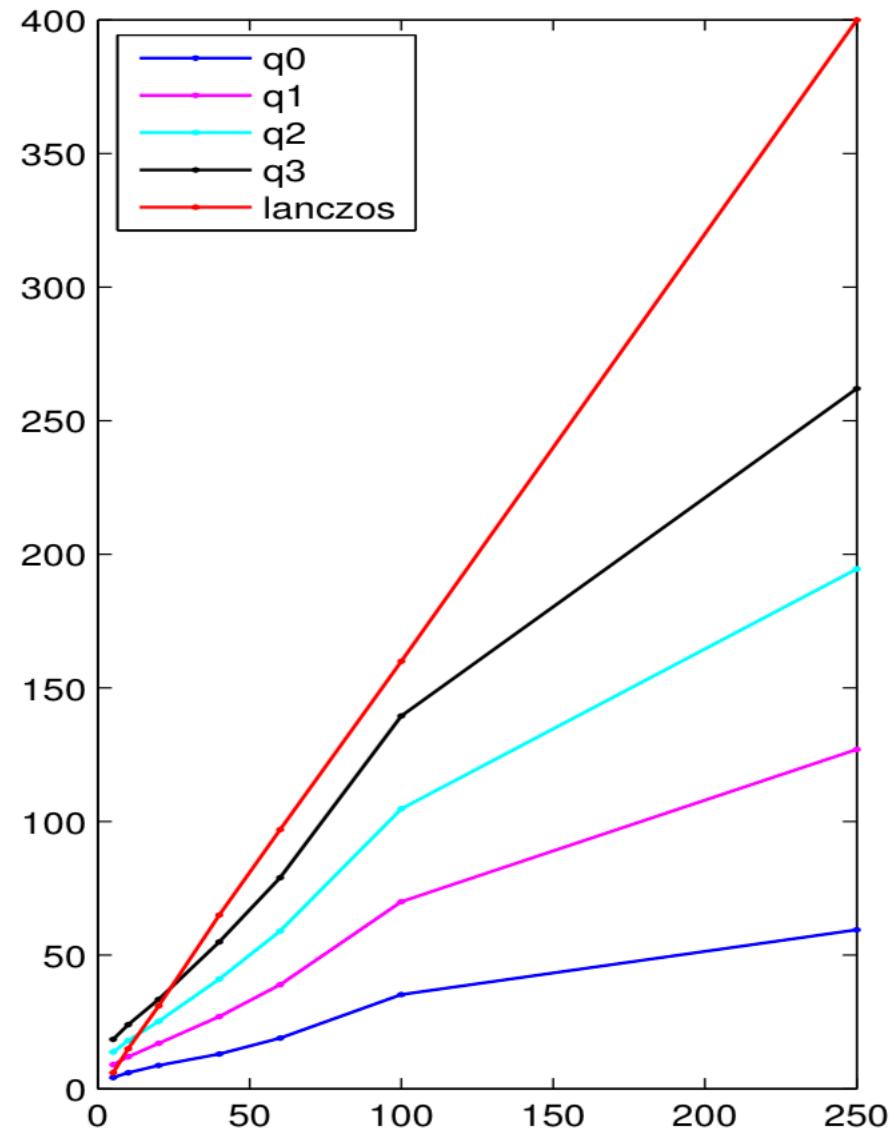
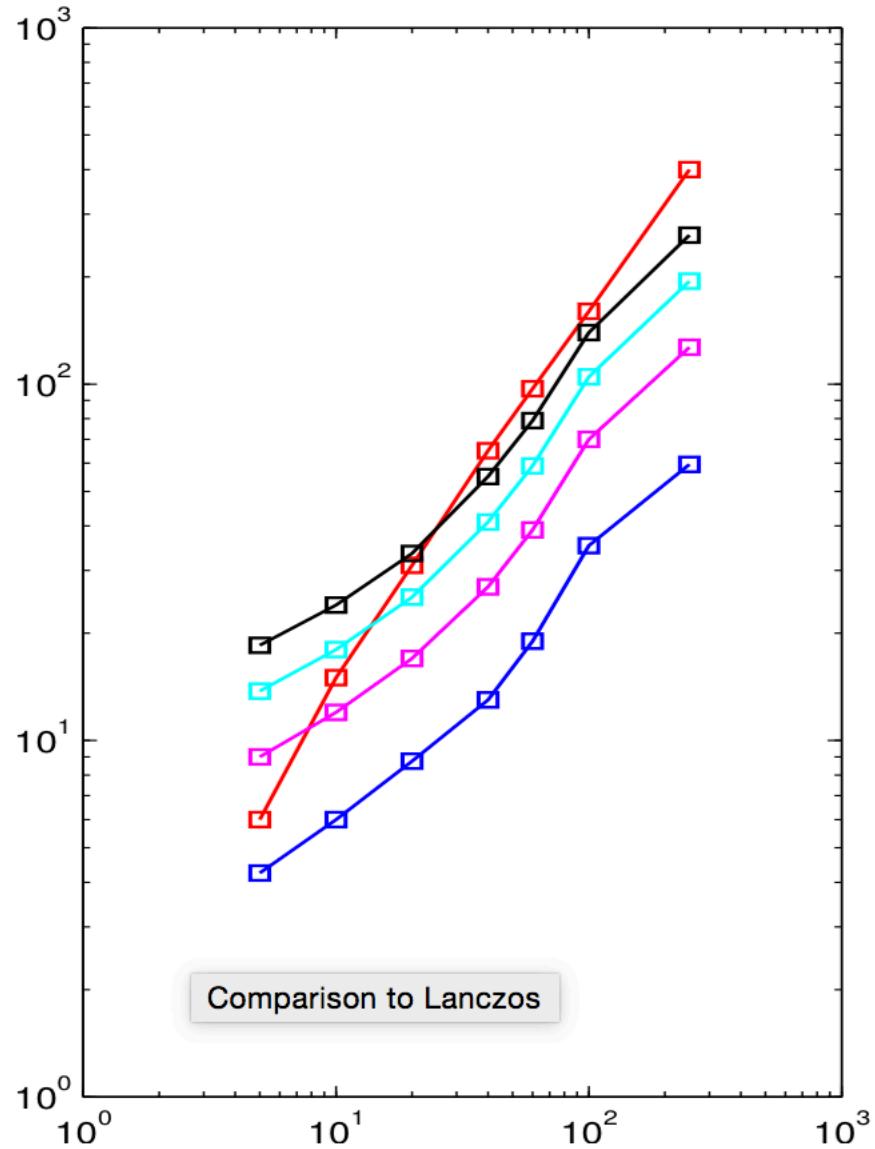
# Comparison to Lanczos

## ALGORITHM 4.8.2: LANCZOS SVD

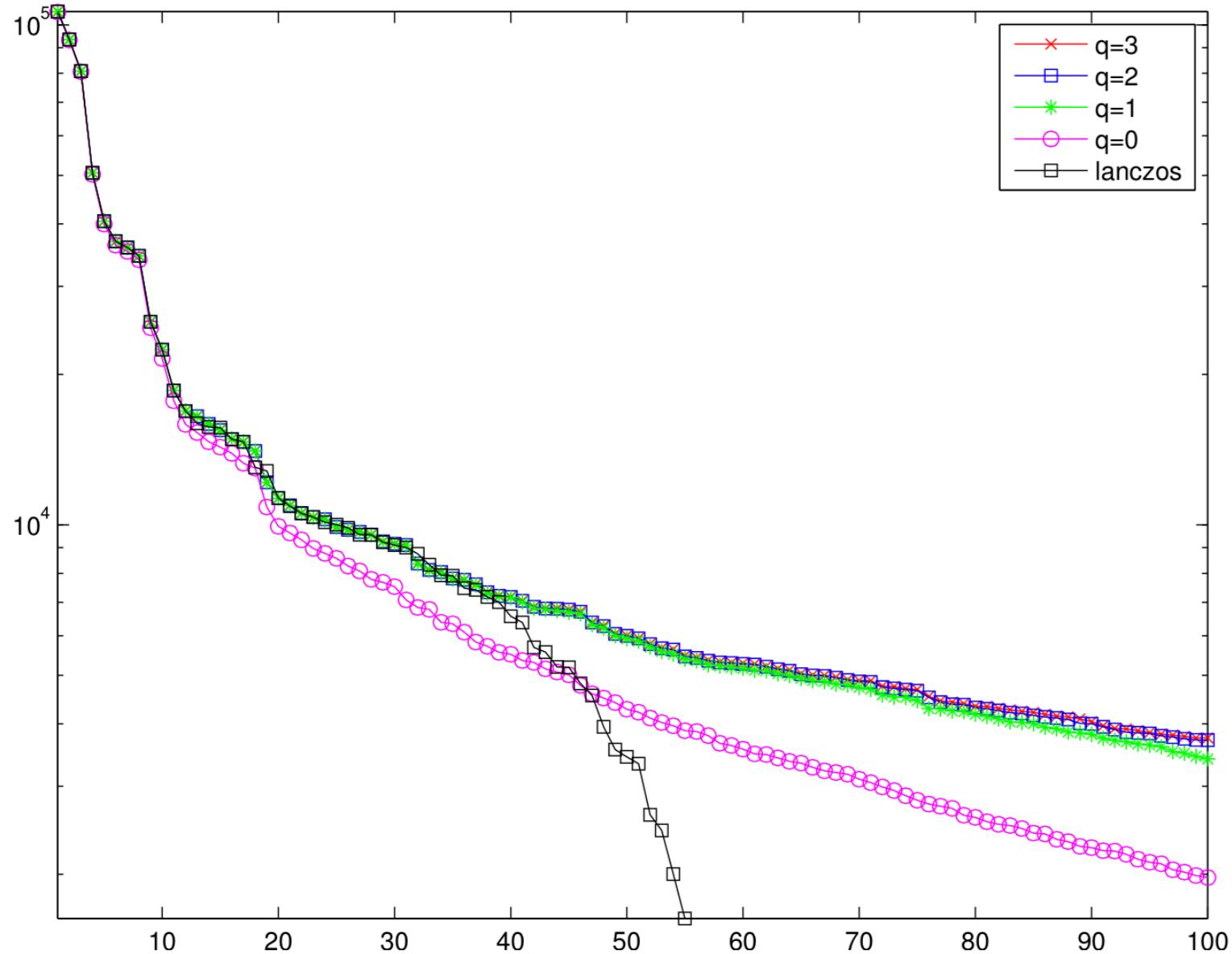
Given an  $m \times n$  matrix  $\mathbf{A}$  and a desired rank  $k$ , Lanczos SVD computes the  $k$  dimensional eigen-decomposition,  $\mathbf{V}\Sigma^2\mathbf{V}^T$ , of  $\mathbf{A}^T\mathbf{A}$  which yields the right singular vectors  $\mathbf{V}$  and singular values  $\Sigma$  of  $\mathbf{A}$ .

```
q = A^T A omega
q1 = q / ||q||
while i ≤ k do
    MapReduce step: Algorithm 4.5
    q = A^T A q_i
    Serial step:
    for j = 1..i
        q ← q - ⟨q_j, q⟩ q_j
        q_{i+1} = q / ||q||
        collect: α, β
    end for
end while
compute XΛX^T = T
V = QX
σ_i = √λ_i
```

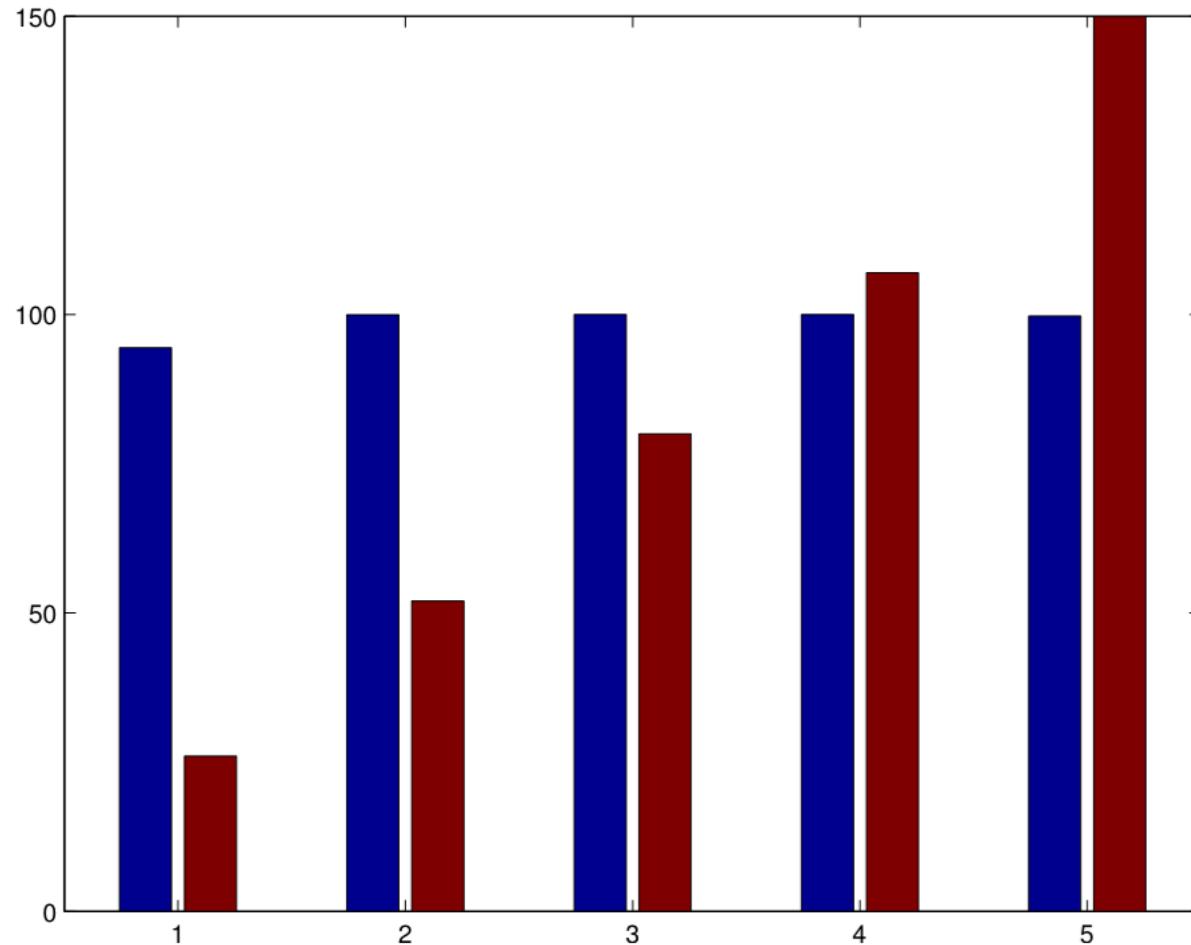
# Comparison to Lanczos



# Comparison to Lanczos



# Comparison to Lanczos



# Datasets

- Wikipedia-all

Execution times	minutes
Q-job	4
Bt-job	49
ABt-job	127
U-job	1.5
V-job	7
$q = 0$	61
$q = 1$	235

- Wikipedia-MAX

phase	time
Q-job	20
Bt-Job	365
ABt-job	571
U-job	8
V-job	14
total	1335

# That's SSVD!



# Resources

- Randomized methods for computing the SVD of very large matrices
  - <http://web.stanford.edu/group/mmds/slides2010/Martinsson.pdf>
- Randomized methods for computing low-rank approximations of matrices
  - [https://amath.colorado.edu/faculty/martinss/Pubs/2012\\_halko\\_dissertation.pdf](https://amath.colorado.edu/faculty/martinss/Pubs/2012_halko_dissertation.pdf)
- SSVD on Mahout
  - <https://mahout.apache.org/users/algorithms/d-ssvd.html>